



# Innovation vs. improvement in eco-evolutionary dynamics

---

Luca Peliti

September 6, 2017

SMRI (Italy)

luca@peliti.org

# Table of contents

---

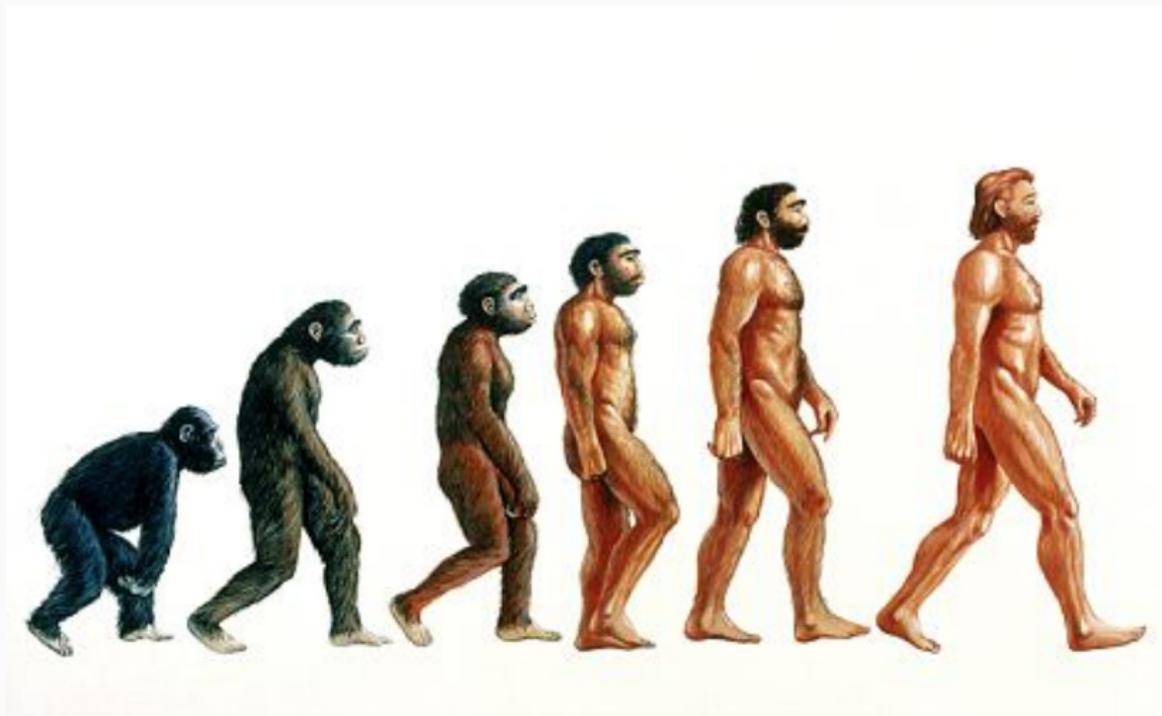
1. Introduction
2. Evolution and ecology: A solvable model
3. Summary

# Evolution as improvement

---

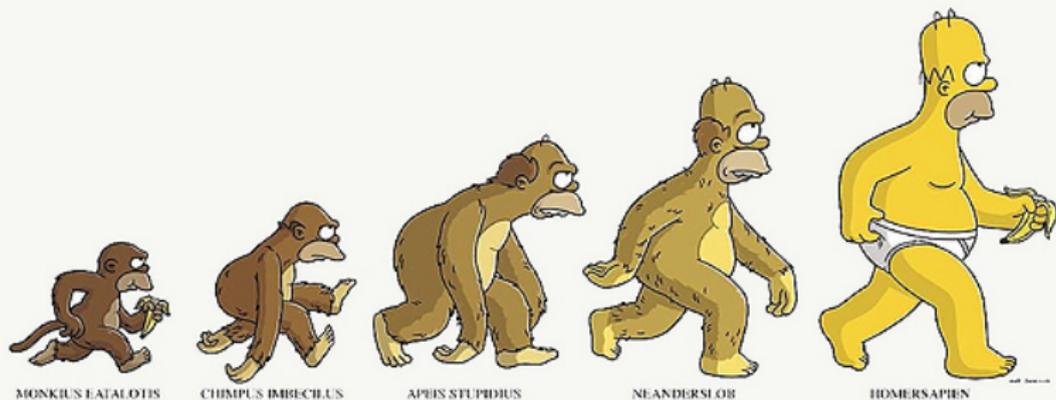
- \* In the classical evolution scenarios, natural selection acts towards the optimization of the species fitness
- \* This is often represented as a tendency of a life form to develop towards “more and more perfect forms”

# Images of evolution



DAILY MAIL

# Images of evolution



MONKIUS LATALOTIS

CHIMPUS IMBECILUS

APEIS STUPIDIUS

NEANDERSLOB

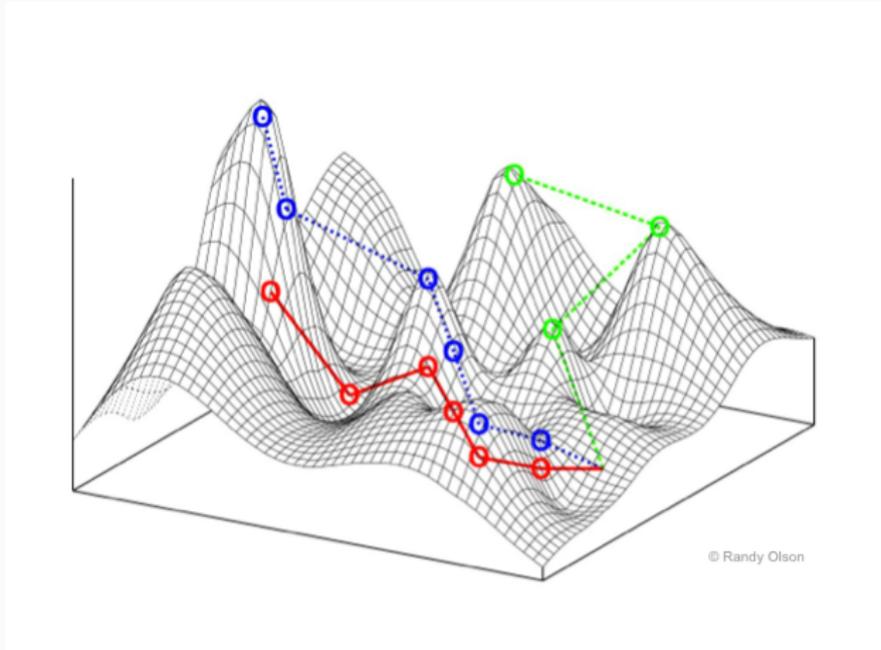
HOMERSAPIEN

HOMERSAPIEN

BITREBELS

# Fitness landscapes

This is often represented by describing life forms as climbing uphill in a *fitness landscape* (WRIGHT, KAUFFMAN, GAVRILETS)



# Scala Naturæ

This is not so different from the medieval concept of *Scala Naturæ*



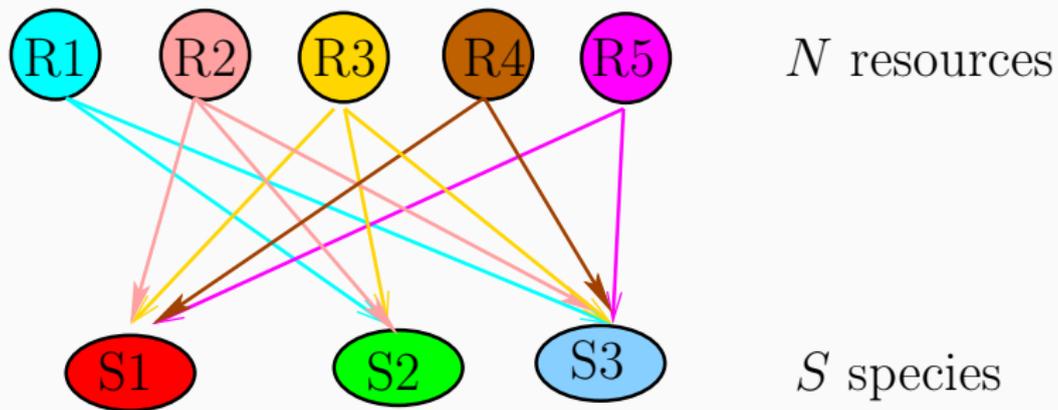
# Evolution and ecology

---

So, why doesn't evolution stop?

- \* The “fitness landscape” is a **seascape**: it changes with time
- \* Most of its changes are due to the evolution of other, coexisting, life forms
- \* We need to understand the coevolution of a **large number** of coexisting life forms
- \* Novel aspects emerge when the number of coexisting life forms is large
- \* In this context, evolution is dominated by **innovation** (“creation” of new niches) rather than improvement (higher efficiency or lower cost)

# MacArthur's model of Resource Competition



MACARTHUR AND LEVINS, 1967

# MacArthur's model of Resource Competition

Resource flux:  $R_i, i = 1, \dots, N$

Population dynamics:  $dn_\mu/dt = b_\mu n_\mu \Delta_\mu(\mathbf{h}), \mathbf{h} = (h_i)$

Resource surplus:  $\Delta_\mu(\mathbf{h}) = \sum_i \sigma_{\mu i} h_i - \chi_\mu, \mu = 1, \dots, S$

Metabolic Strategies:  $\sigma_\mu = (\sigma_{\mu 1}, \dots, \sigma_{\mu N})$

Total demand:  $T_i(\mathbf{n}) = \sum_\mu \sigma_{\mu i} n_\mu$

Resource availability:  $h_i = R_i/T_i = H_i(T_i)$

Feedback loop:

- \* Growth of exploiting population leads to decrease in availability
- \* Decrease in availability leads to decrease in population growth

Lyapunov function (MACARTHUR, 1969):

$$F(\mathbf{n}) = \sum_i R_i \log T_i(\mathbf{n}) - \sum_\mu n_\mu \chi_\mu$$

$$\frac{dF}{dt} = \sum_\mu b_\mu n_\mu \Delta_\mu^2 \geq 0$$

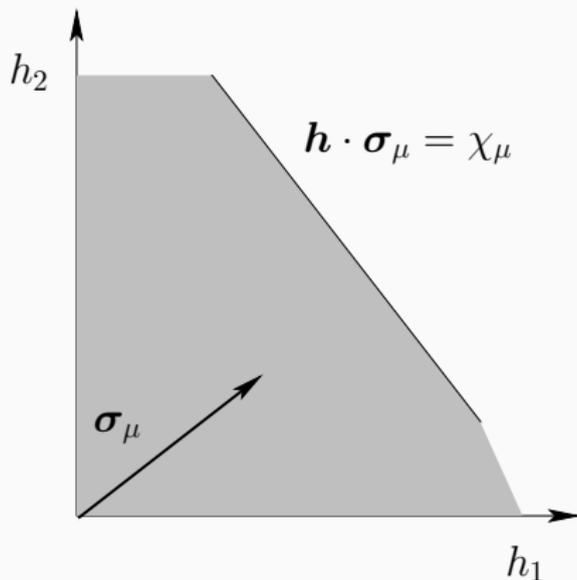
Global optimization of  $F$  for a given set of strategies and cost

# MacArthur's model of Resource Competition

Steady state:

- \* If  $n_\mu > 0$ ,  $\Delta_\mu = 0$ , i.e.,  $\mathbf{h} \cdot \boldsymbol{\sigma}_\mu = \chi_\mu$
- \* If  $n_\mu = 0$ ,  $\mathbf{h} \cdot \boldsymbol{\sigma}_\mu < \chi_\mu$  ("forbidden region")

Geometric interpretation (TILMAN, 1982):

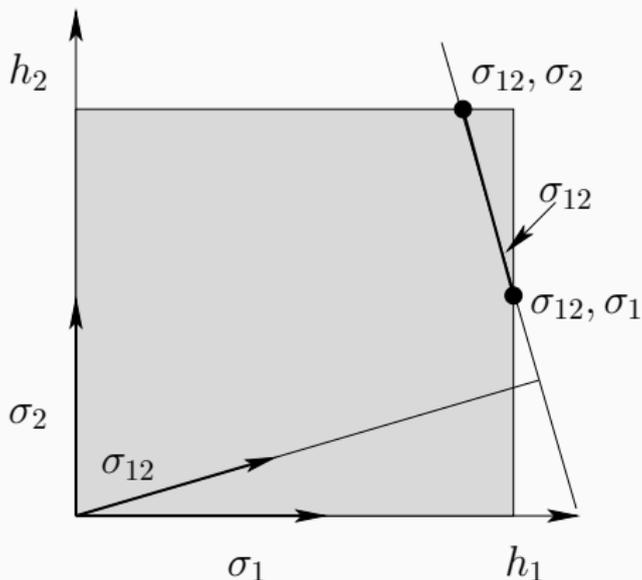


# MacArthur's model of Resource Competition

Steady state:

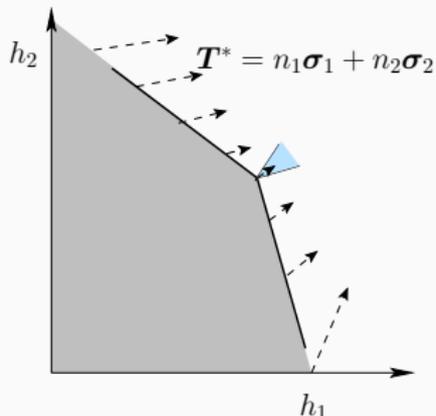
- \*  $\sigma_1, \sigma_2$  are "specialists" with cost  $\chi_0$
- \*  $\sigma_{12}$  is a "generalist" with cost  $\chi_{12} < \chi_0$

The steady state contains  $\sigma_{12}$  and possibly one of  $\sigma_1$  or  $\sigma_2$ :



## Locating the steady state

- \* At the steady state  $\mathbf{h}^*$ ,  $\mathbf{n}^*$ , the vector of total demand  $\mathbf{T}(\mathbf{n}^*)$  must point *strictly outward* from the unsustainable (gray) region, since  $\mathbf{T}^* = \sum_{\mu} n_{\mu} \boldsymbol{\sigma}_{\mu}$
- \* Define a vector field  $\mathbf{T}_0(\mathbf{h})$  such that  $T_{0i}(\mathbf{h}) = R_i/h_i$ , then  $\mathbf{T}_0(\mathbf{h}^*) = \mathbf{T}^*$
- \* Thus follow the vector field  $\mathbf{T}_0$  along the boundary of the unsustainable region, till locating where it points strictly outwards



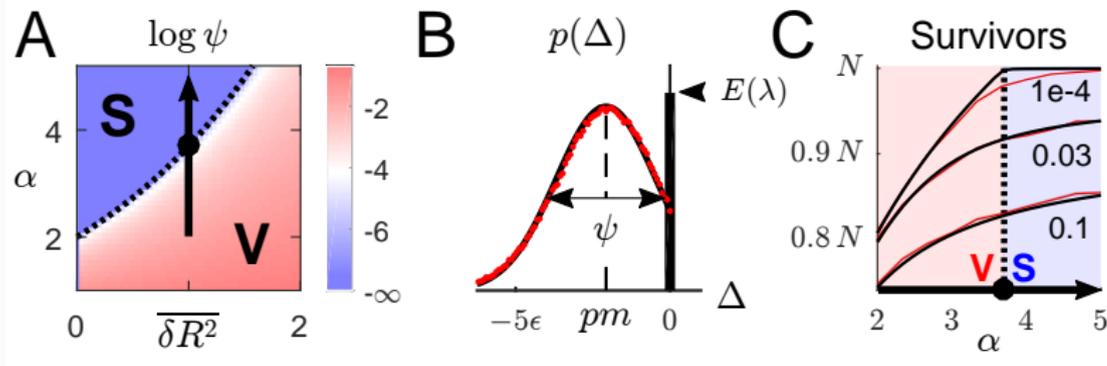
# MacArthur's model in large dimensionality

What happens when  $N \gg 1$ ?

- \* M. TIKHONOV (2015) introduced MacArthur's model with quenched disorder to the statphys community
- \* Several researchers analyzed the model in large dimensions by statphys methods (replica, cavity method): TIKHONOV himself, and ADVANI, BUNIN, MEHTA, MONASSON, ...
- \* TIKHONOV and MONASSON find a phase transition in large ecosystems:
  - V phase:** "vulnerable": The number of surviving species is much smaller than  $N$ , the system is vulnerable to a change of external conditions
  - S phase:** "stable": There are exactly  $N$  species which can adapt to change in external conditions without going extinct
- \* More recently, they analyzed the evolutionary implications of the model

# The transition

- \*  $\sigma_{\mu i} = 1$  with probability  $p$  (else 0),  $\chi_{\mu} = \sum_i \sigma_{\mu i} + \epsilon x_{\mu}$
- \* Control parameters:  $N, \alpha = S/N, p, \epsilon, \overline{\delta R^2}$
- \* Order parameters:  $m = \bar{h}, \psi = (\overline{h_i - \bar{h}})^2$

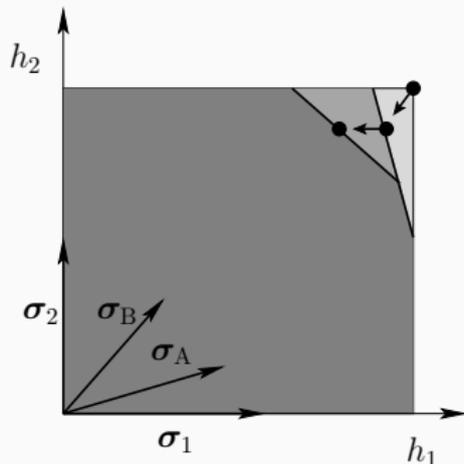


TIKHONOV AND MONASSON, 2016

# Evolution of communities

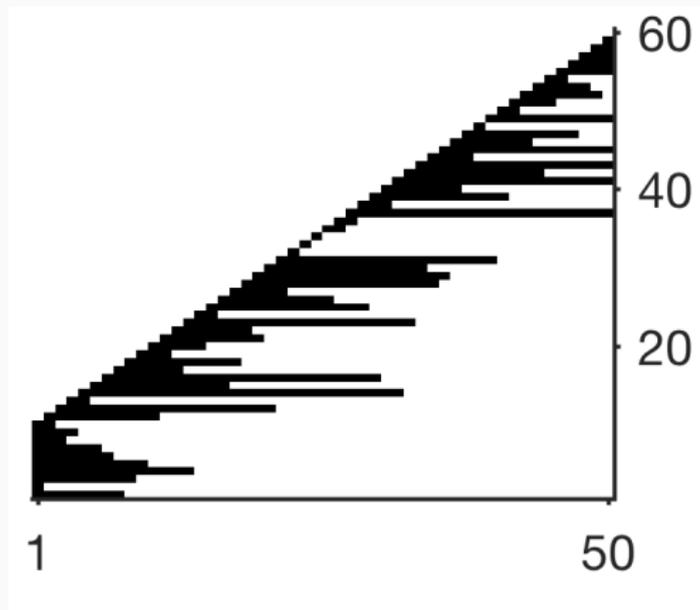
- \* # of possible species:  $2^N \gg N$
- \* Keep introducing new species ( $\alpha = S(t)/N$  measures time)
- \* Let the system reach steady state each time
- \* Allow “extinct” species to resurrect

Is “resurrection” moot?



# Cost optimization?

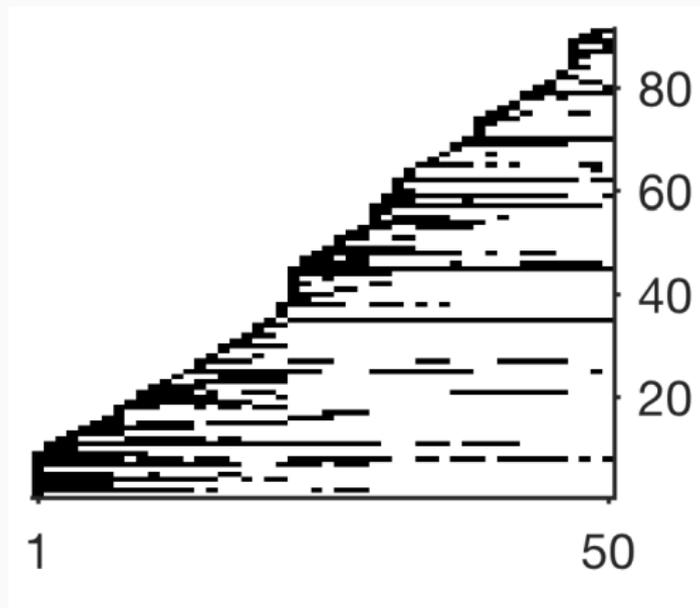
The “best species” model:



TIKHONOV AND MONASSON, 2017

## Cost optimization?

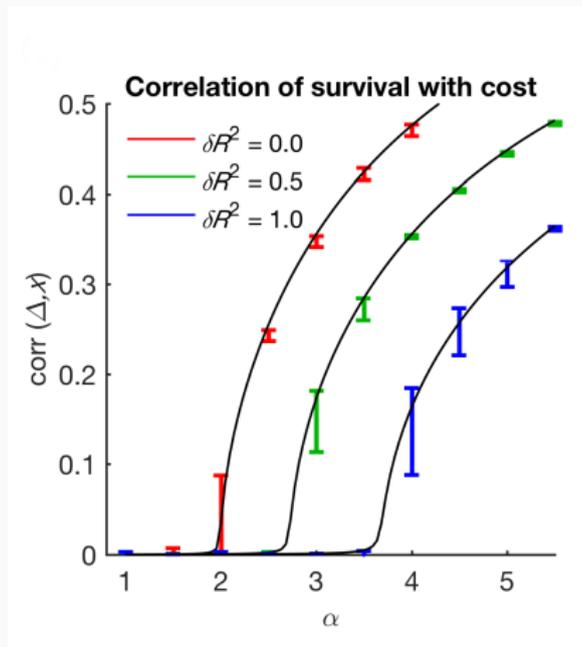
The actual simulation ( $N = 15$ ,  $\overline{\delta R^2} = 1.5$ ):



TIKHONOV AND MONASSON, 2017

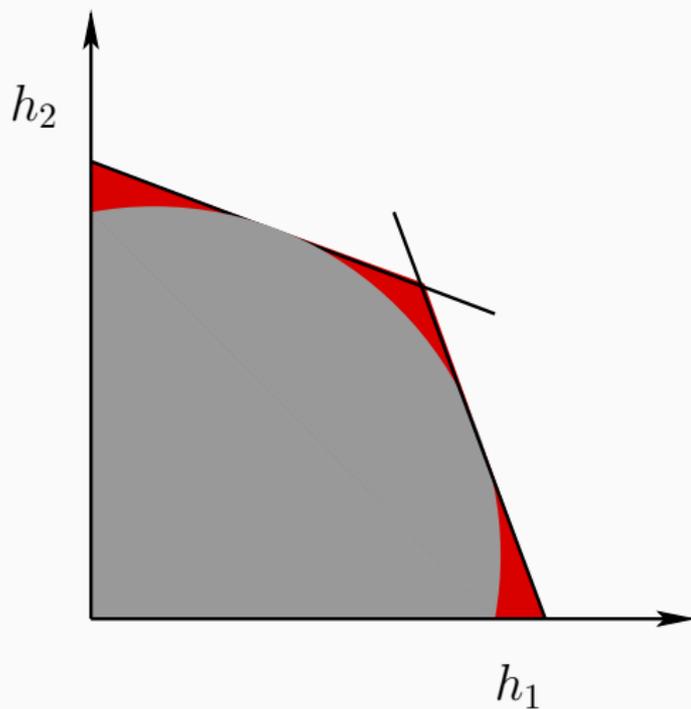
## Is cost relevant?

For  $\alpha = S/N < \alpha_C$ , the correlation between  $x_\mu$  (cost) and  $\Delta_\mu$  (viability) vanishes:

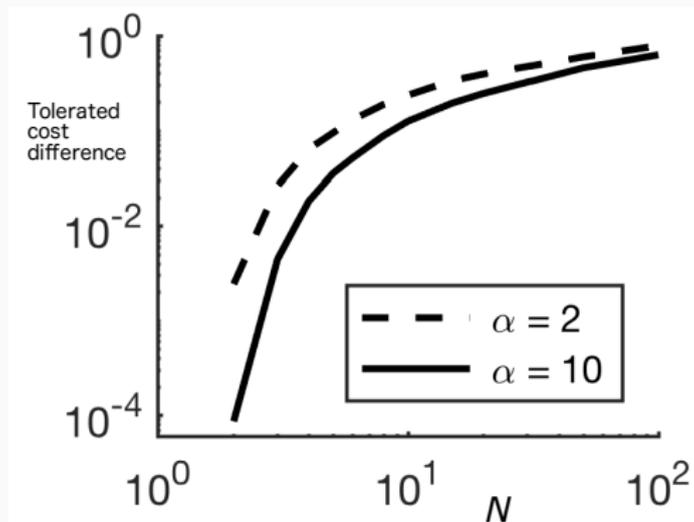


# Is cost relevant?

Tolerated cost in the presence of random strategies of cost 1:

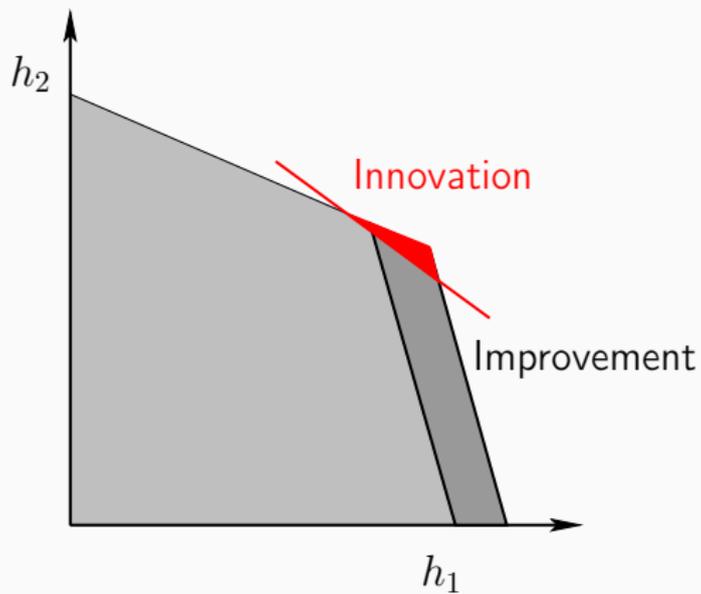


# Tolerated cost difference for large $N$



TIKHONOV AND MONASSON, 2017

# Invasion strategies at large $N$



TIKHONOV AND MONASSON, 2017

# Summary

---

- \* Complex ecosystems may work in a “shielded” regime, which is not vulnerable to fluctuations in the outside environment
- \* This obtains by the introduction of species which operate a workable compromise in resource consumption, while cost is of lesser importance
- \* In large dimensionality, the room for innovation is exponentially larger than that of improvement (innovation as “environmental engineering”)
- \* Is a “one-dimensional” fitness concept a good cue in this situation?

## Caveats:

- \* The model is very simple (no RSP)
- \* As soon as “producers” appear, there’s no Lyapunov function
- \* Good starting point (cf. HOPFIELD’s model)?

Thank you!